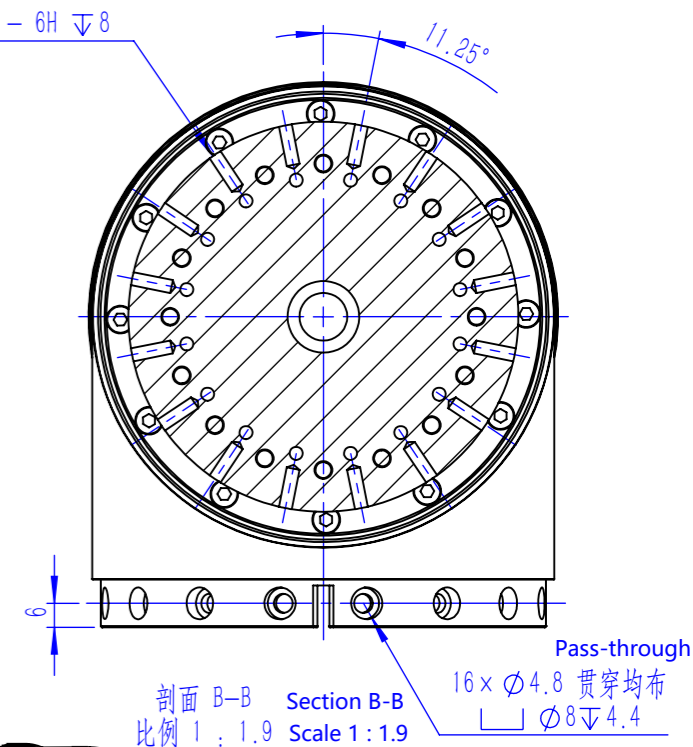
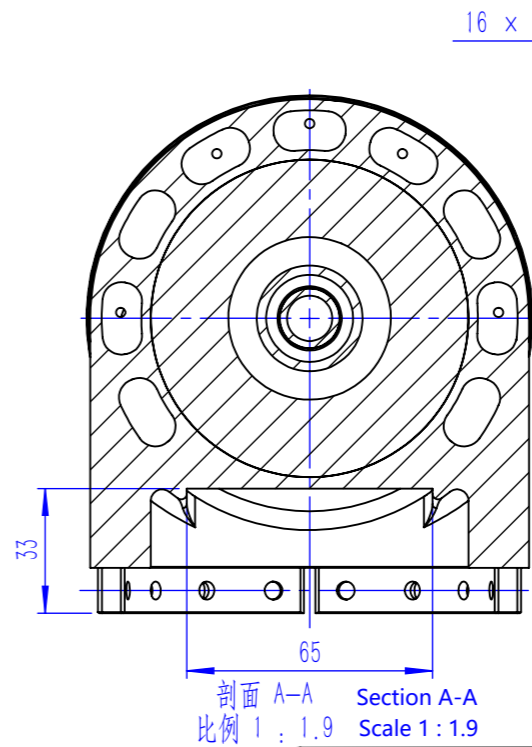
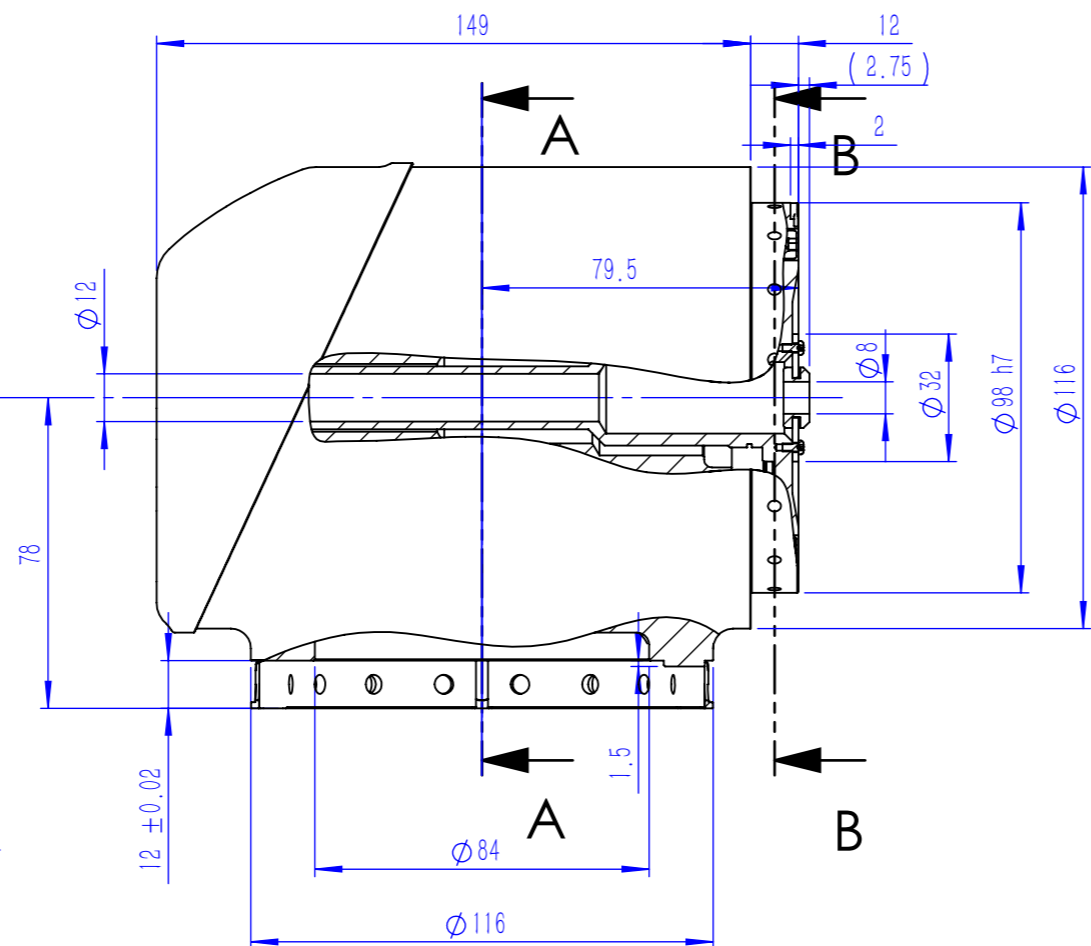
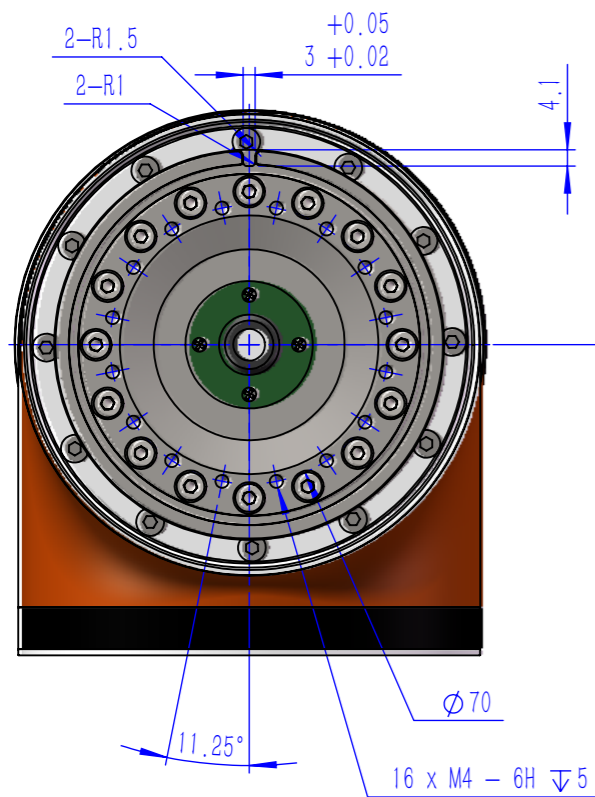
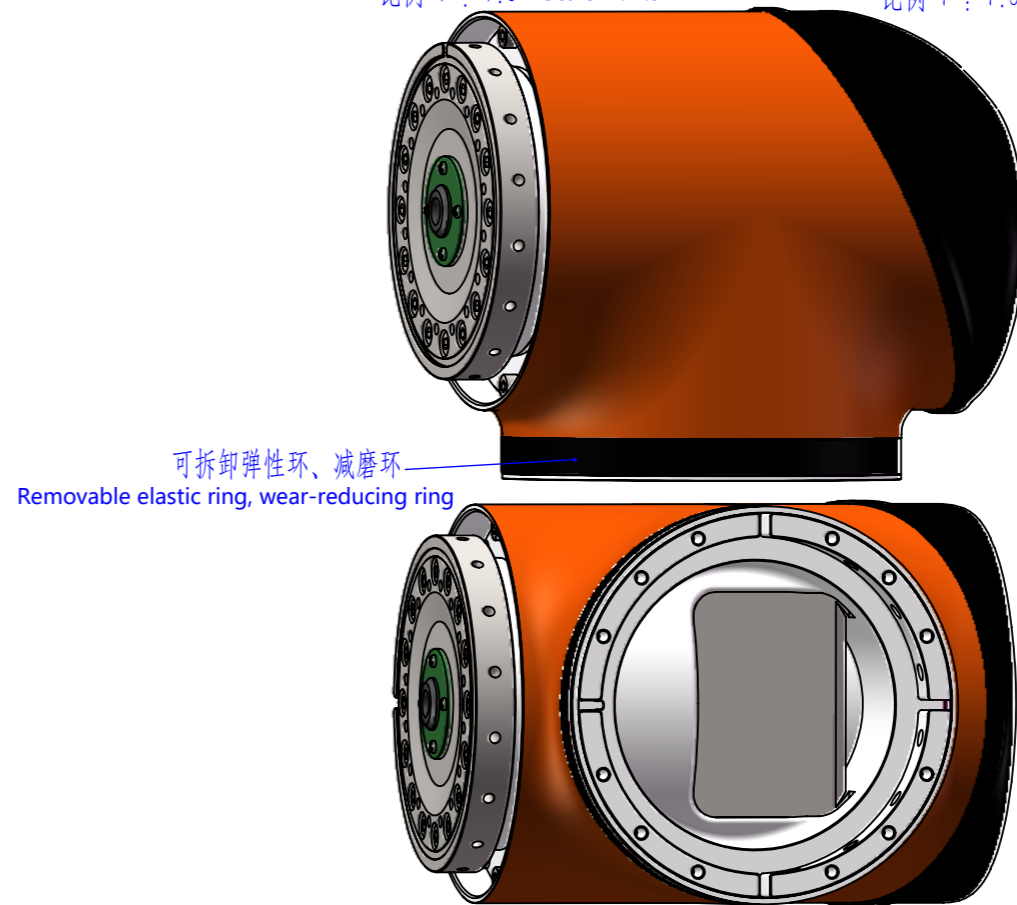
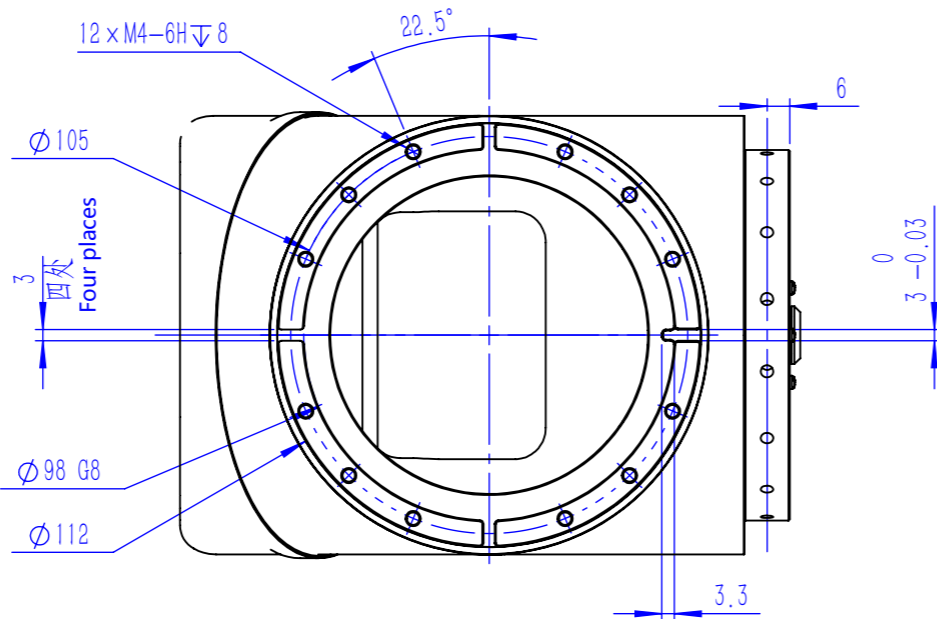


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机械参数 Mechanical Parameters	单位 Units	数值 Values
减速器速比 Reducer Ratio	—	101
减速器背隙 Reducer Backlash	arcsec	10
转动精度 Rotational Accuracy	arcmin	1
平均负载转矩 Average Load Torque	N·m	133
启停容许转矩 Start/Stop Allowable Torque	N·m	194
静态负载转矩 Static Load Torque	N·m	160
最大瞬时转矩 Maximum Instantaneous Torque	N·m	351
最大许用弯矩 Maximum Permissible Bending Moment	N·m	243
最大瞬时弯矩 Maximum Momentary Bending Moment	N·m	480
额定转速 Rated Speed	rpm	29.7
最大转速 Maximum Speed	rpm	37.6
关节重量 Joint Weight	kg	4.5
关节直径 Joint Diameter	mm	116
关节长度 Joint Length	mm	149

电气参数 Motor Parameters	单位 Units	数值 Values
极对数 Number of Poles	—	6
额定功率 Rated Power	W	400
额定电压 Rated Voltage	VDC	48
额定电流 Maximum Power	Arms	11.5
额定转速 Rated Speed	rpm	3000
额定转矩 Rated Torque	N·m	1.4
转矩常数 Torque constant	N·m/A	0.15
线反电动势 Back Electromotive Force Coefficient	V/krpm	9.8
抱闸 Brake	—	24/12VDC电磁摩擦片式 24/12VDC Electromagnetic Friction Plate
输出端反馈 Output feedback	—	17-bit单圈绝对值 17bit single-turn absolute value
电机反馈 Motor feedback	—	UVW霍尔+20000P/R增量编码器 UVW Hall + 20000 P/R Incremental Encoder
通讯接口 Communication Interface	—	EtherCAT/CANopen



技术说明

1. 紧固螺钉需采用12.9级或以上螺钉并按标准拧紧；
2. 若采用径向连接方式，关节公母端连接接口设计建议按关节的公母端结构尺寸；
3. 101、161速比可选；
4. 支持OEM客户定制。

Technical Description

1. Use screws of Class 12.9 or higher and tighten according to standard specifications.
2. If using a radial connection method, the joint male and female end connection interface design is recommended to be based on the structural dimensions of the joint's male and female ends.
3. Reducer ratios of 101 and 161 are optional.
4. Supports OEM customization.



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